

emfbadge16

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2017

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1 bytebeat/0001-enable-pyb.DAC-digital-to-analog-convertor-api.patch

From 8bed55122b601e530c8e4e9d12467323d0b5a6fa Mon Sep 17 00:00:00 2001

From: Claude Heiland-Allen <claude@mathr.co.uk>

Date: Thu, 2 Mar 2017 12:55:20 +0000

Subject: [PATCH 1/2] enable pyb.DAC digital to analog convertor api

5

stmhal/boards/STM32L475_EMFBADGE/mpconfigboard.h | 1 +
1 file changed, 1 insertion(+)

10 diff --git a/stmhal/boards/STM32L475_EMFBADGE/mpconfigboard.h b/stmhal/boards/STM32L475_EMFBADGE/mpconfigboard.h

index be029221..6fa81ed1 100644

--- a/stmhal/boards/STM32L475_EMFBADGE/mpconfigboard.h

+++ b/stmhal/boards/STM32L475_EMFBADGE/mpconfigboard.h

@@ -12,6 +12,7 @@

15 #define MICROPY_HW_ENABLE_RTC (1)

#define MICROPY_HW_ENABLE_TIMER (1)

#define MICROPY_HW_ENABLE_SERVO (1)

+#define MICROPY_HW_ENABLE_DAC (1)

#define MICROPY_HW_HAS_UGFX (1)

20 #define MICROPY_HW_HAS_CC3100 (1)

#define MICROPY_HW_L4_512_FS (1)

--

2.11.0

2 bytebeat/0002-Revert-stmhal-dac-DAC-deinit-method-added.patch

From 04bbba79308f93c3db87de23e3646b1da0496041 Mon Sep 17 00:00:00 2001

From: Claude Heiland-Allen <claude@mathr.co.uk>

Date: Thu, 2 Mar 2017 13:28:24 +0000

Subject: [PATCH 2/2] Revert "stmhal/dac: DAC deinit() method added."

5

This reverts commit 641300dccb0a68e4ede07323aabeed564a892a8f.

docs/library/pyb.DAC.rst | 4 ----

```

10      stmhal/dac.c          | 16 -----
10      2 files changed, 20 deletions(-)

diff --git a/docs/library/pyb.DAC.rst b/docs/library/pyb.DAC.rst
index 4b9651e2..f0d4de4c 100644
--- a/docs/library/pyb.DAC.rst
15 +++ b/docs/library/pyb.DAC.rst
@@ -67,10 +67,6 @@ Methods

    Reinitialise the DAC. ``bits`` can be 8 or 12.

20  -.. method:: DAC.deinit()
-
-    De-initialise the DAC making its pin available for other uses.
-
.. method:: DAC.noise(freq)
25

    Generate a pseudo-random noise signal. A new random sample is written

diff --git a/stmhal/dac.c b/stmhal/dac.c
index 7493bb59..bb700883 100644
--- a/stmhal/dac.c
30 +++ b/stmhal/dac.c
@@ -246,21 +246,6 @@ STATIC mp_obj_t pyb_dac_init(mp_uint_t n_args, const mp_obj_t *args,
                            mp_map_t *k
{
}
STATIC MP_DEFINE_CONST_FUN_OBJ_KW(pyb_dac_init_obj, 1, pyb_dac_init);

35  -/// \method deinit()
-/// Turn off the DAC, enable other use of pin.
-STATIC mp_obj_t pyb_dac_deinit(mp_obj_t self_in) {
-    pyb_dac_obj_t *self = self_in;
-    if (self->dac_channel == DAC_CHANNEL_1) {
40        DAC_Handle.Instance->CR &= ~DAC_CR_EN1;
-        DAC_Handle.Instance->CR |= DAC_CR_BOFF1;
-    } else {
-        DAC_Handle.Instance->CR &= ~DAC_CR_EN2;
-        DAC_Handle.Instance->CR |= DAC_CR_BOFF2;
45    }
-    return mp_const_none;
-}
-STATIC MP_DEFINE_CONST_FUN_OBJ_1(pyb_dac_deinit_obj, pyb_dac_deinit);
-
50  #if defined(TIM6)
// \method noise(freq)
// Generate a pseudo-random noise signal. A new random sample is written
@@ -476,7 +461,6 @@ STATIC MP_DEFINE_CONST_FUN_OBJ_KW(pyb_dac_write_timed_obj,
                                1, pyb_dac_write_time
STATIC const mp_map_elem_t pyb_dac_locals_dict_table[] = {
55    // instance methods
    { MP_OBJ_NEW_QSTR(MP_QSTR_init), (mp_obj_t)&pyb_dac_init_obj },
-   { MP_OBJ_NEW_QSTR(MP_QSTR_deinit), (mp_obj_t)&pyb_dac_deinit_obj },
-   { MP_OBJ_NEW_QSTR(MP_QSTR_write), (mp_obj_t)&pyb_dac_write_obj },
-   #if defined(TIM6)
60       { MP_OBJ_NEW_QSTR(MP_QSTR_noise), (mp_obj_t)&pyb_dac_noise_obj },
--
```

2.11.0

3 bytebeat/main.py

```

#### Author: Claude Heiland-Allen
#### Description: Live coding byte beat synth
#### Category: Music
#### License: MIT
5 #### Appname : ByteBeat

import buttons
import imu
import ugfx
10 import pyb
import array
import math

code = (">> ", "&", "f", "t", "t"], [])
15 buttons.init()
accel = imu.IMU()
ugfx.init()

20 ugfx.clear(ugfx.BLACK)
ugfx.set_default_font(ugfx.FONT_TITLE)
s = ugfx.Style()
s.set_enabled([ugfx.WHITE, ugfx.WHITE, ugfx.WHITE, ugfx.WHITE])
s.set_pressed([ugfx.WHITE, ugfx.WHITE, ugfx.WHITE, ugfx.WHITE])
25 s.set_disabled([ugfx.WHITE, ugfx.WHITE, ugfx.WHITE, ugfx.WHITE])
s.set_focus(ugfx.BLACK)
s.set_background(ugfx.BLACK)
ugfx.set_default_style(s)

30 bytecode = array.array('i', [])

opcodes = { "~": 0x100, "<": 0x200, "=": 0x300, ">": 0x400, "%": 0x500, "/": 0x600,
        "*": 0x700, "t": 0x800, "+": 0xa00, "-": 0xb00, "<<": 0xc00, ">>": 0xd00,
        "^": 0xe00, "|": 0xf00, "&": 0x1000 }

@micropython.asm_thumb
35 def interpret_asm(r0, r1, r2): # t, bytecode array, bytecode array length
    # save stack
    push({r10})
    mov(r10, r13)
    # clear stack underflow safety buffer
40    mov(r3, 0)
    push({r3})
    push({r3})
    push({r3})
    push({r3})
    push({r3})
    push({r3})
45    push({r3})
    push({r3})
    push({r3})
    push({r3})
    push({r3})
    push({r3})
    push({r3})
50    push({r3})
    push({r3})
    push({r3})
    # for r3 in [0..length)

```

```

55      cmp( r3 , r2 )
      blt(LOOP)
      b(DONE)
      label(LOOP)

56      ldr( r4 , [r1 , 0] )
# r4 contains bytecode (2 bytes)
      add(r1 , r1 , 4)
      mov(r5 , r4)
      mov(r6 , 8)
      lsr(r5 , r6)
57      # r5 contains opcode flag

58      # ~
59      cmp(r5 , 0x1)
      ittt(eq)
60      pop({r6})
      mvn(r6 , r6)
      push({r6})
      b(NEXT)
      # <
61      cmp(r5 , 0x2)
      bne(SKIP2)
      pop({r6 , r7})
      cmp(r7 , r6)
      ite(lt)
62      mov(r6 , 1)
      mov(r6 , 0)
      push({r6})
      b(NEXT)
      label(SKIP2)
63      # ==
64      cmp(r5 , 0x3)
      bne(SKIP3)
      pop({r6 , r7})
      cmp(r6 , r7)
      ite(eq)
65      mov(r6 , 1)
      mov(r6 , 0)
      push({r6})
      b(NEXT)
      label(SKIP3)
66      # >
67      cmp(r5 , 0x4)
      bne(SKIP4)
      pop({r6 , r7})
68      cmp(r7 , r6)
      ite(gt)
      mov(r6 , 1)
      mov(r6 , 0)
      push({r6})
      b(NEXT)
      label(SKIP4)
69      # %
70      # no modulo instruction , so do a % b = a - (a / b) * b
      cmp(r5 , 0x5)
      bne(SKIP5)

```

```

pop({r6, r7})
cmp(r6, 0)
it(eq)
mov(r6, 1)
115    sdiv(r5, r7, r6) # safe to use r5 as we'll branch to NEXT
        mul(r5, r6) # look into mls() instruction?
        sub(r7, r7, r5)
        push({r7})
        b(NEXT)
120    label(SKIP5)
        # /
        cmp(r5, 0x6)
        bne(SKIP6)
        pop({r6, r7})
125    cmp(r6, 0)
        it(eq)
        mov(r6, 1)
        sdiv(r7, r7, r6)
        push({r7})
        b(NEXT)
130    label(SKIP6)
        # *
        cmp(r5, 0x7)
        ittt(eq)
135    pop({r6, r7})
        mul(r6, r7)
        push({r6})
        b(NEXT)
        # t
140    cmp(r5, 0x8)
        itt(eq)
        push({r0})
        b(NEXT)
        # 0
145    cmp(r5, 0x9)
        ittt(eq)
        mov(r6, 0xFF)
        and_(r4, r6)
        push({r4})
150    b(NEXT)
        # +
        cmp(r5, 0xA)
        ittt(eq)
        pop({r6, r7})
155    add(r6, r6, r7)
        push({r6})
        b(NEXT)
        # -
        cmp(r5, 0xB)
160    ittt(eq)
        pop({r6, r7})
        sub(r7, r7, r6)
        push({r7})
        b(NEXT)
165    # <<
        cmp(r5, 0xC)
        ittt(eq)

```

```

pop({r6, r7})
lsl(r7, r6)
push({r7})
b(NEXT)
# >>
170      cmp(r5, 0xD)
ittt(eq)
pop({r6, r7})
asr(r7, r6)
push({r7})
b(NEXT)
# ^
175      cmp(r5, 0xE)
ittt(eq)
pop({r6, r7})
eor(r6, r7)
push({r6})
b(NEXT)
# |
180      cmp(r5, 0xF)
ittt(eq)
pop({r6, r7})
orr(r6, r7)
push({r6})
b(NEXT)
# &
185      cmp(r5, 0x10)
ittt(eq)
pop({r6, r7})
and_(r6, r7)
push({r6})

190      # done
label(NEXT)
add(r3, r3, 1)
cmp(r3, r2)
blt(LOOP)
195      label(DONE)
pop({r0})
mov(r3, 0xFF)
and_(r0, r3)
# restore stack
200      mov(r13, r10)
pop({r10})

def interpret(bytecode, t):
    # pad with 16x 0 in case of underflow...
215      stack = [0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0]
    n = len(bytecode)
    i = 0
    while i < n:
        b = bytecode[i]
        o = b >> 8
        if o == 1:
            stack = [~stack[0]] + stack[1:]
        elif o == 2:
            stack = [int(stack[1] < stack[0])] + stack[2:]
220

```

```

225             elif o == 3:
226                 stack = [int(stack[1] == stack[0])] + stack[2:]
227             elif o == 4:
228                 stack = [int(stack[1] > stack[0])] + stack[2:]
229             elif o == 5:
230                 if stack[0] == 0:
231                     stack = [stack[1] % 1] + stack[2:]
232                 else:
233                     stack = [stack[1] % stack[0]] + stack[2:]
234             elif o == 6:
235                 if stack[0] == 0:
236                     stack = [stack[1] / 1] + stack[2:]
237                 else:
238                     stack = [stack[1] / stack[0]] + stack[2:]
239             elif o == 7:
240                 stack = [stack[1] * stack[0]] + stack[2:]
241             elif o == 8:
242                 stack = [t] + stack
243             elif o == 9:
244                 stack = [b & 0xFF] + stack
245             elif o == 0xa:
246                 stack = [stack[1] + stack[0]] + stack[2:]
247             elif o == 0xb:
248                 stack = [stack[1] - stack[0]] + stack[2:]
249             elif o == 0xc:
250                 stack = [stack[1] << stack[0]] + stack[2:]
251             elif o == 0xd:
252                 stack = [stack[1] >> stack[0]] + stack[2:]
253             elif o == 0xe:
254                 stack = [stack[1] ^ stack[0]] + stack[2:]
255             elif o == 0xf:
256                 stack = [stack[1] | stack[0]] + stack[2:]
257             elif o == 0x10:
258                 stack = [stack[1] & stack[0]] + stack[2:]
259             i = i + 1
260         return stack[0] & 0xff

# double buffering
t = 0
which = 0
265 block = (bytearray(256), bytearray(256))
def interprets():
    global bytecode
    global t
    global block
    global which
270    b = block[which]
    n = len(bytecode)
    i = 0
    while i < 256:
        # b[i] = interpret(bytecode, t + i)
        b[i] = interpret_asm(t + i, bytecode, n)
        i = i + 1
    t = (t + 256) & 0x3fffffff

280 dac = pyb.DAC(2)

```

```
def callback(timer):
    global block
    global which
    global dac
    dac.write_timed(block[which], 8192, mode=pyb.DAC.NORMAL)
    which = 1 - which
    interprets()
285

290 timer = pyb.Timer(8)
timer.init(freq=32)

def opcode(s):
    global opcodes
    try:
        o = opcodes[s]
    except:
        o = 0x900 | (int("0x" + s) & 0xFF)
    return o
295

300

def preprocess(code):
    c = list(reversed(code[0])) + code[1]
    n = len(c)
    i = 0
    while i < n:
        c[i] = opcode(c[i])
        i = i + 1
    return array.array('i', c)
305

310 cursor = "@"

def text(code):
    global cursor
    return "\n".join([" ".join(reversed(code[0])), cursor, " ".join(code[1])])
315

source = ugfx.Label(0, 32, 320, 240 - 64, text(code), justification=ugfx.Label.CENTER)
timeout = 0

320 def update(code):
    global source
    source.text(text(code))

325 def left():
    global code
    if len(code[0]) > 0:
        code = (code[0][1:], [code[0][0]] + code[1])
        update(code)

330 def right():
    global code
    if len(code[1]) > 0:
        code = ([code[1][0]] + code[0], code[1][1:])
        update(code)
335

def delete():
```

```
global code
global bytecode
if len(code[0]) > 0:
    code = (code[0][1:] , code[1])
    update(code)
    bytecode = preprocess(code)

345 choosing = False
inserting = False

cursors = [ "~" , "<" , "=" , ">" , "%" , "/" , "*" , "t" , "t" , "+" , "-" , "<<" , ">>" ,
        "^^" , "|" , "&" ]

def choose():
350     global code
     global cursors
     global cursor
     global accel
     a = accel.get_acceleration()
     x = a['x']
     y = a['y']
     r = x * x + y * y
     p = 0.5 + 0.5 * math.atan2(-y, x) / math.pi
     if r > 0.2:
360         cursor = hex(int(0xFF * p + 0.5) & 0xFF)[2:]
     else:
365         cursor = cursors[int(0x10 * p + 0.5) & 0xF]
     update(code)

370 def commit(inserting):
     global code
     global cursor
     global bytecode
     if inserting:
         code = ([cursor] + code[0] , code[1])
     elif len(code[0]) > 1:
         code = ([cursor] + code[0][1:] , code[1])
         cursor = "@"
         update(code)
375     bytecode = preprocess(code)

     update(code)
     bytecode = preprocess(code)
     timer.callback(callback)

380 while not buttons.is_pressed("BTN_MENU"):
     if choosing and not buttons.is_pressed("BTN_A") and not buttons.
         ↴ is_pressed("BTN_B"):
             choosing = False
             commit(inserting)
             timeout = 2
     if buttons.is_pressed("BTN_A") and not buttons.is_pressed("BTN_B"):
385         choosing = True
         inserting = True
         choose()
     if not buttons.is_pressed("BTN_A") and buttons.is_pressed("BTN_B"):
390         choosing = True
```

```

            inserting = False
            choose()
    if timeout == 0:
        if buttons.is_pressed("JOY_LEFT"):
            left()
            timeout = 2
        if buttons.is_pressed("JOY_RIGHT"):
            right()
            timeout = 2
    400   if buttons.is_pressed("JOY_CENTER"):
            delete()
            timeout = 2
    else:
        timeout = timeout - 1
405   t2 = t
    x = (t2 & 0xFF) + 0x20
    y = (t2 >> 8) & 0x1F
    b = block[which]
    410   ugfx.stream_start(x, y, 256, 1)
    i = 0
    while i < 256:
        o = b[i]
        c = o | (o << 8)
    415   ugfx.stream_color(c)
        i = i + 1
    ugfx.stream_stop()
    pyb.wfi()

```

4 bytebeat/README.md

bytebeat

algorithmic symphonies from reverse polish notation

5 targetting emfcamp 2016 badge tilda mk3

install

10 -----

needs modified firmware (compiled with dac support), these instructions modified from those at: https://badge.emfcamp.org/wiki/TiLDA_MK3/build

15 set up variable to bytebeat sources (directory containing this readme):

export bytebeat=/path/to/bytebeat/

debian packages for the cross-compiler exist, no need for ppa:

20 sudo apt-get install gcc-arm-none-eabi

getting the source:

25 git clone --recursive <https://github.com/emfcamp/micropython.git>
cd micropython
git checkout tilda-master

```
apply dac-enabling patches:  
30     git checkout -b enable-dac  
     git am $bytebeat/000*.patch  
  
build:  
35     make -C stmhal BOARD=STM32L475_EMFBADGE  
  
flash to tilde in dfu mode (press joystick center with rear reset button):  
40     make -C stmhal BOARD=STM32L475_EMFBADGE deploy      # untested by me...  
  
you can also reflash (this method tested by me) with the update.py from  
https://badge.emfcamp.org/wiki/TiLDA_MK3/Firmware_Update  
but you need to patch it so it doesn't automatically download fresh firmware  
45 from the internet and delete it afterwards:  
  
50         cd stmhal/build-STM32L475_EMFBADGE  
         wget https://update-badge.emfcamp.org/update.py  
         patch -p1 < $bytebeat/update-py*.patch  
         python update.py  
  
you need to let the badge connect to wifi and download the base system now.  
  
finally, mount the badge and copy the program:  
55         export badge=/mnt/badge  
         sudo mkdir -p $badge  
         sudo mount /dev/sdwhatever $badge  
         sudo mkdir -p $badge/apps/clause~bytebeat/  
60         sudo cp $bytebeat/main.py $badge/apps/clause~bytebeat/main.py  
  
alternatively, you can run with pyboard.py to send over usb one-shot (useful  
for development), see:  
https://badge.emfcamp.org/wiki/TiLDA_MK3/Get_Started#5._Run_a_whole_file_of_code  
65  
  
controls  
-----  
  
70     joystick left/right to navigate (@ cursor shows current selection for A/B press)  
  
     joystick center press to delete previous item  
  
     hold button A with accelerometer to insert new items on release  
75     hold button B with accelerometer to modify previous item on release  
  
     small tilts choose operators (including t)  
  
80     large tilts choose values (8bit hex)  
  
     menu button to quit
```

```

85  electronics
-----
audio out on pin X6 PB2 (8bit , 8kHz, 0V–3.3V) , connect to minijack ring
(with 100uF AC coupling capacitor?)

90  connect X 0V pin to minijack sleeve (with resistor?)

problems with mains hum due to touching pcb ground , consider making a case

```

5 bytebeat/update-py-no-download-and-delete-firmware.patch

```

--- old/update.py      2017-03-02 12:40:47.607835323 +0000
+++ new/update.py     2017-03-05 00:51:30.632207263 +0000
@@ -22,7 +22,6 @@
    import usb.core
5   import usb.util
    import zlib
-import urllib
    import os

10  # VID/PID
@@ -522,9 +521,6 @@
        init()
        print("We found your badge. So far, so good...")

15  -     print("Please wait while we download the latest version of the badge ↵
    ↴ software...")
-     urllib.URLopener().retrieve("https://update.badge.emfcamp.org/firmware. ↵
    ↴ dfu", "firmware.dfu")
-     print("Done")
-     print("Please wait, we're now running the update")

20  elements = read_dfu_file("firmware.dfu")
@@ -543,8 +539,6 @@
        print("To put your badge into DFU mode you need to press the joystick ↵
            ↴ in the middle while pressing the reset button at the back.")
        print()
        print("Error: %s" %(e))
25  -     finally:
-         if "firmware.dfu" in os.listdir("."): os.remove("firmware.dfu")

if __name__ == '__main__':
    main()

```